

Probability Refresher

Chapter 3: Random vectors

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Outline

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- 2 Joint and marginal densities
- 3 Independence of random variables
- 4 Covariance
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Random vectors I

- A **random vector** is the collection of a finite number of random variables X_1, \dots, X_d in a vector $X = (X_1, \dots, X_d) \in \mathbb{R}^d$.
- The **joint distribution** of $X = (X_1, \dots, X_d)$, denoted by \mathbb{P}_X or $\mathbb{P}_{(X_1, \dots, X_d)}$, is the measure on \mathbb{R}^d defined by

$$\mathbb{P}_X(A) = \mathbb{P}((X_1, \dots, X_d) \in A).$$

- The distribution of an element X_k of a random vector $X = (X_1, \dots, X_d)$ is called the **marginal distribution** of X_k .
- The **cumulative distribution function** $F_X : \mathbb{R}^d \rightarrow [0, 1]$ of X is defined by

$$F_X(t_1, \dots, t_d) = \mathbb{P}(X_1 \leq t_1, \dots, X_d \leq t_d), \quad (t_1, \dots, t_d)^T \in \mathbb{R}^d.$$

Random vectors II

- The **characteristic function** $\Phi_X : \mathbb{R}^d \rightarrow \mathbb{C}$ of X is defined as

$$\Phi_X(\mathbf{t}) = \mathbb{E} \left[e^{i\mathbf{t}^T \mathbf{X}} \right] = \mathbb{E} \left[\exp \left\{ i \sum_{k=1}^d t_k X_k \right\} \right], \quad \mathbf{t} = (t_1, \dots, t_d)^T \in \mathbb{R}^d.$$

- The **mean vector** of X is the column vector of the expectations of the elements of X given by

$$\mathbb{E}[\mathbf{X}] = \begin{pmatrix} \mathbb{E}[X_1] \\ \mathbb{E}[X_2] \\ \vdots \\ \mathbb{E}[X_d] \end{pmatrix}.$$

Joint and marginal densities I

Definition

We say that (X, Y) has **joint density** $f : \mathbb{R}^2 \rightarrow \mathbb{R}_+$ if for any set $A \subset \mathbb{R}^2$

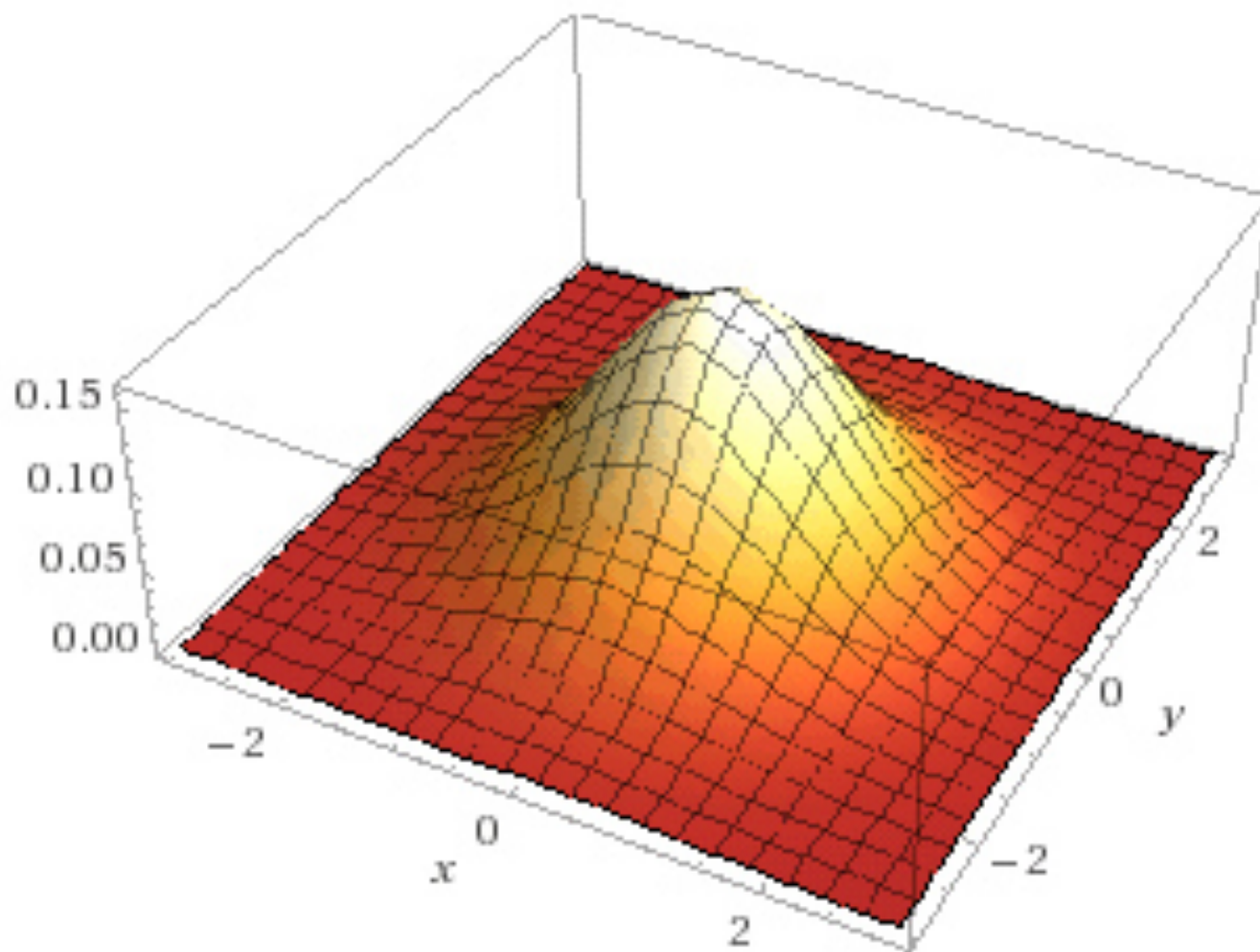
$$\mathbb{P}((X, Y) \in A) = \iint_A f(x, y) dx dy.$$

In this case, for every function ϕ ,

$$\mathbb{E}[\phi(X, Y)] = \iint_{\mathbb{R}^2} \phi(x, y) f(x, y) dx dy.$$

This quantity is well-defined either if $\phi \geq 0$ or if $\iint |\phi| f < +\infty$.

Joint and marginal densities II



Joint density of (X, Y) , where X and Y are independent $\mathcal{N}(0, 1)$.

Joint and marginal densities III

Definition

Let (X, Y) be a random vector. If the marginal distribution of X (or Y) is continuous, its density is called the **marginal density of X** (or Y).

Proposition

Let (X, Y) be a random vector with density $f(x, y)$. Then X has a density f_X given by

$$f_X(x) = \int_{\mathbb{R}} f(x, y) dy$$

Likewise, Y has density f_Y given by $f_Y(y) \mapsto \int_{x \in \mathbb{R}} f(x, y) dx$.

Joint and marginal densities IV

Exercise

Let (X, Y) be a random vector with density $f(x, y) = (x + y)\mathbb{1}_{[0,1] \times [0,1]}(x, y)$.

- Show that f is indeed a density.
- Compute the marginal density of X .

Joint and marginal densities V

It occurs that X and Y both have densities, while the random vector (X, Y) has not.

Exercise

- Let $X \sim \mathcal{E}(1)$ and $Y = 2X$.
- Note that the random vector (X, Y) lies on the line $D = \{y = 2x\}$ almost surely, that is $\mathbb{P}((X, Y) \in D) = 1$.
- Show that (X, Y) is not continuous.

Independence of random variables I

Definition

Let X_1, X_2, \dots be random variables defined on the same probability space (Ω, \mathbb{P}) .

- We say that X_1, \dots, X_n are (mutually) **independent** if for all events B_1, \dots, B_n ,

$$\mathbb{P}(X_1 \in B_1, X_2 \in B_2, \dots, X_n \in B_n) = \prod_{i=1}^n \mathbb{P}(X_i \in B_i).$$

- We say that the random variables X_1, X_2, \dots are **independent and identically distributed (i.i.d.)** if, for every n , X_1, \dots, X_n are independent and the random variables X_i have all the same law.

Independence of random variables II

Proposition

- Let X_1, X_2, \dots, X_n be independent and integrable random variables. Then

$$\mathbb{E}[X_1 X_2 \dots X_n] = \mathbb{E}[X_1] \mathbb{E}[X_2] \dots \mathbb{E}[X_n]$$

Proposition

- Let X_1, X_2, \dots, X_n be independent and ϕ_1, \dots, ϕ_n be some functions. Then

$X \perp Y$
 $\Rightarrow x^2 \perp e^{-y}$
 $\phi_1(X_1), \phi_2(X_2), \dots, \phi_n(X_n)$ independent (\perp)

- If, moreover, $\phi_k(X_k) \in L^1$, then

$$\mathbb{E}[x^2 e^{-y}] = \mathbb{E}[x^2] \mathbb{E}[e^{-y}]$$

$$\mathbb{E}[\phi_1(X_1) \phi_2(X_2) \dots \phi_n(X_n)] = \mathbb{E}[\phi_1(X_1)] \mathbb{E}[\phi_2(X_2)] \dots \mathbb{E}[\phi_n(X_n)]$$

Independence of random variables III

Proposition

For any random variables X_1, \dots, X_n the following assertions are equivalent:

i X_1, \dots, X_n are *independent*

ii The cumulative distribution function F_X of the random vector $X = (X_1, \dots, X_n)$ can be factorized as follows

$$\begin{aligned} & \text{--- } P(X_1 \leq t_1, \dots, X_n \leq t_n) \\ F_X(t_1, \dots, t_n) &= F_{X_1}(t_1) \dots F_{X_n}(t_n) \quad \forall t_1, \dots, t_n \in \mathbb{R} \end{aligned}$$

iii The characteristic function Φ_X of the random vector $X = (X_1, \dots, X_n)$ can be factorized as follows

$$\begin{aligned} & e^{a+b} = e^a e^b \quad \text{--- } E\left[\exp\left\{i \sum_{k=1}^n t_k X_k\right\}\right] = E\left[\prod_{k=1}^n e^{it_k X_k}\right] \\ \Phi_X(t_1, \dots, t_n) &= \prod_{k=1}^n \phi_{X_k}(t_k) \quad \forall t_k \in \mathbb{R} \end{aligned}$$

Independence of random variables IV

Proposition

Let X and Y be two random variables.

- i If X and Y are independent and continuous with densities f_X and f_Y , then the random vector (X, Y) is continuous with density

$$f_{(X,Y)}(x,y) = f_X(x) f_Y(y)$$

- ii Conversely, if (X, Y) has a density $f_{(X,Y)}$ and if there are functions g_1 and g_2 such that the joint density can be written as a product

$$f_{(X,Y)}(x,y) = g_1(x)g_2(y), \quad \text{for (almost) all } x, y \in \mathbb{R},$$

then X, Y are independent.

$$F_{(X,Y)}(x,y) \stackrel{!}{=} F_X(x) F_Y(y)$$

$$f_{(X,Y)}(x,y) = \frac{\partial}{\partial x} \frac{\partial}{\partial y} F_{(X,Y)}(x,y)$$

$$\stackrel{!}{=} \frac{\partial}{\partial x} F_X(x) \cdot \frac{\partial}{\partial y} F_Y(y) = f_X(x) f_Y(y)$$

Independence of random variables V

$$\begin{aligned} g_1(x) &= 6x^2 \mathbb{1}_{[0,1]}(x) = c_1 f_X(x) \\ g_2(y) &= y \mathbb{1}_{[0,1]}(y) = c_2 f_Y(y) \end{aligned}$$

Exercise

Let (X, Y) be a random vector with density $f(x, y) = 6x^2 y \mathbb{1}_{(x,y) \in [0,1]^2}$.

- Show that X and Y are independent. ✓
- Determine the marginal densities of X and Y .

$$\begin{aligned} &= g_1(x) g_2(y) \\ &= \frac{1}{c_1 c_2} \mathbb{1}_{[0,1]}(x) \mathbb{1}_{[0,1]}(y) \end{aligned}$$

Independence of random variables VI

Independent continuous random variables never take the same value:

Proposition

Let X_1, X_2, \dots be a sequence of independent random variables with densities $f_k, k = 1, 2, \dots$. Then the random variables X_1, X_2, \dots are all pairwise distinct with probability one, that is,

$$\mathbb{P}(X_i \neq X_j, \forall i \neq j) = 1$$

Sums of independent random variables I

Let X and Y be random variables. What can we say about $X + Y$?

- By linearity of the expectation

$$\mathbb{E}[X + Y] = \mathbb{E}[X] + \mathbb{E}[Y].$$

- If X and Y are **independent**,

$$\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y).$$

$$\begin{aligned} & \mathbb{E}[(X+Y)^2] - (\mathbb{E}[X+Y])^2 \\ &= \mathbb{E}[X^2] + \cancel{2\mathbb{E}[XY]} + \mathbb{E}[Y^2] - (\mathbb{E}[X])^2 - \cancel{2\mathbb{E}[X]\mathbb{E}[Y]} - (\mathbb{E}[Y])^2 \\ & \quad \quad \quad = \mathbb{E}[X]\mathbb{E}[Y] \quad \quad \quad \end{aligned}$$

Sums of independent random variables II

Theorem

Let X and Y be independent random variables with densities f and g . Then the sum $X + Y$ has a density given by

$$f_{X+Y}(t) = f * g(t),$$

where $u \mapsto f * g(u)$ is the **convolution function** of f and g defined as

$$f * g(u) = \int_{x \in \mathbb{R}} f(x)g(u - x)dx.$$

Sums of independent random variables III

Exercise

- Let X and Y be i.i.d. with the exponential distribution $\mathcal{E}(1)$, i.e. with density $f(x) = e^{-x}\mathbb{1}_{x \geq 0}$.
- Compute the density of the sum $U = X + Y$.

Sums of independent random variables IV

The characteristic function is an efficient tool to handle sums of independent random variables.

Proposition

Let X and Y be independent random variables. Then the characteristic function of the sum $X + Y$ is given by

$$\begin{aligned}\Phi_{X+Y}(t) &= \phi_X(t) \phi_Y(t) \\ \mathbb{E}[\exp\{i(X+Y)t\}] &= \mathbb{E}[e^{iXt} \cdot e^{iYt}] \\ &\stackrel{\text{I.I.}}{=} \mathbb{E}[e^{iXt}] \mathbb{E}[e^{iYt}]\end{aligned}$$

Sums of independent random variables V

- Let X and Y be independent and normally distributed with $X \sim \mathcal{N}(\mu_1, \sigma_1^2)$ and $Y \sim \mathcal{N}(\mu_2, \sigma_2^2)$.
- Then $X + Y$ is also a gaussian random variable with

$$X_1 + X_2 \sim \mathcal{N}(\mu_1 + \mu_2, \sigma_1^2 + \sigma_2^2).$$

- For the proof uses the characteristic function of the normal distribution $\mathcal{N}(\mu, \sigma^2)$ given by

$$\Phi_X(t) = \exp\left(it\mu - \frac{t^2\sigma^2}{2}\right).$$

Covariance I

Definition

Let X and Y be random variables in L^2 . The **covariance** of X and Y is defined by

$$\begin{aligned}\text{Cov}(X, Y) &= \mathbb{E}[(X - \mathbb{E}[X])(Y - \mathbb{E}[Y])] \\ &= \mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y].\end{aligned}$$

$= \mathbb{E}[X] \mathbb{E}[Y] \text{ if } \underline{Y = c}$

$Y = c \text{ constant} = c\mathbb{E}[X] - \mathbb{E}[X] \cdot c = 0$

Covariance II

Proposition

Let $X, Y, X_i, Y_j \in L^2$.

- i (Symmetry) $\text{Cov}(X, Y) = \text{Cov}(Y, X)$.
- ii (Bilinearity) For any constants $a_i, b_j \in \mathbb{R}$,

$$\text{Cov} \left(\sum_i a_i X_i, \sum_j b_j Y_j \right) = \sum_i a_i \sum_j b_j \text{Cov}(X_i, Y_j)$$

- iii $\text{Cov}(X, X) = \text{Var}(X)$
- iv If X and Y are independent, $\text{Cov}(X, Y) = 0$
- v For any constant c , $\text{Cov}(X, c) = 0$ $\text{Cov}(X+c, Y) = \text{Cov}(X, Y)$
- vi $\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y) + 2 \text{Cov}(X, Y)$

Covariance III

Definition

Let $X = (X_1, \dots, X_d)$ be a random vector such that $X_k \in L^2$ for $k = 1, \dots, d$. The **covariance matrix** $\text{Cov}(X)$ of X is the $d \times d$ matrix with entries $\text{Cov}(X_i, X_j)$. More precisely,

$$\text{Cov}(X) = (\text{Cov}(X_i, X_j))_{i,j} = \begin{matrix} & j \\ & \vdots \\ i & \left(\begin{array}{ccc} \dots & \text{Cov}(X_i, X_j) & \dots \end{array} \right) \\ & \vdots \end{matrix}.$$

Covariance IV

Example

- Let X_1, \dots, X_d be i.i.d.
- The covariance matrix of $X = (X_1, \dots, X_d)$ is given by

$$\text{Cov}(X) = \begin{pmatrix} \sigma^2 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \sigma^2 \end{pmatrix}, \quad = \sigma^2 \underset{\substack{\text{identity matrix} \\ = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \in \mathbb{R}^{d \times d}}}{I_d}$$

where $\sigma^2 = \text{Var}(X_1)$.

Covariance V

Using vector and matrix notation, we obtain an expression of the covariance matrix that is easier to handle.

Proposition

$$\text{Cov}(X) = \mathbb{E} \left[(X - \mathbb{E}[X])(X - \mathbb{E}[X])^T \right].$$

Proposition

- i Any covariance matrix $\text{Cov}(X)$ is symmetric.
- ii Any covariance matrix $\text{Cov}(X)$ is positive semi-definite, i.e. for all $t = (t_1, \dots, t_d) \in \mathbb{R}^d$ we have $t^T \text{Cov}(X) t \geq 0$.

Covariance VI

For linear transformations of a random vector, there are simple formulas for the mean and the covariance matrix.

Proposition

Let $X \in \mathbb{R}^d$ be a random vector with finite covariance matrix. Let M be a $p \times d$ matrix and $a \in \mathbb{R}^p$ a vector. Then the mean and the covariance vector of the random vector $MX + a \in \mathbb{R}^p$ are given by

$$\begin{aligned}\mathbb{E}[MX + a] &= M \mathbb{E}[X] + a \quad \text{and} \quad \text{Cov}(MX + a) = \text{Cov}(MX) = M \text{Cov}(X) M^T \\ &= \mathbb{E}[(MX - \mathbb{E}MX)(MX - \mathbb{E}MX)^T] \\ &= \mathbb{E}\left[M(X - \mathbb{E}X) \cdot \underbrace{(M(X - \mathbb{E}X))^T}_{= (X - \mathbb{E}X)^T M^T}\right] \\ &= M \text{Cov}(X) M^T\end{aligned}$$

Correlation I

Definition

Let $X, Y \in L^2$ and $\text{Var}(X) > 0$ and $\text{Var}(Y) > 0$. The **correlation** or **Pearson's correlation coefficient** between X and Y is defined by

$$\rho_{X,Y} = \frac{\text{Cov}(X, Y)}{\sqrt{\text{Var}(X)\text{Var}(Y)}}.$$

We say that X and Y have

- **positive correlation** if $\rho_{X,Y} > 0$ and
- **negative correlation** if $\rho_{X,Y} < 0$.

Correlation II

- If $X \perp Y$, then $\rho_{X,Y} = 0$.
- The correlation is invariant with respect to affine transformations: for any $a \neq 0$, $b \neq 0$ $c, d \in \mathbb{R}$,

$$\rho_{aX+c, bY+d} = \text{sign}(ab)\rho_{X,Y},$$

where $\text{sign}(u) = \mathbb{1}\{u > 0\} - \mathbb{1}\{u < 0\}$.

Correlation III

Theorem

- $-1 \leq \rho_{X,Y} \leq 1$.
- $\rho_{X,Y} = 1 \iff \exists a > 0, b \in \mathbb{R}$ such that $Y = aX + b$ a.s.
- $\rho_{X,Y} = -1 \iff \exists a < 0, b \in \mathbb{R}$ such that $Y = aX + b$ a.s.

The correlation $\rho_{X,Y}$ measures the degree of **linear** dependence between X and Y .